

CONNECTION BETWEEN THE RENORMALIZATION GROUPS OF STÜCKELBERG–PETERMANN AND WILSON

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The Stückelberg–Petermann renormalization group is the group of finite renormalizations of the S -matrix in the framework of causal perturbation theory. The renormalization group in the sense of Wilson relies usually on a functional integral formalism, it describes the dependence of the theory on a UV-cutoff Λ ; a widespread procedure is to construct the theory by solving Polchinski’s flow equation for the effective potential.

To clarify the connection between these different approaches we proceed as follows: in the framework of causal perturbation theory we introduce an UV-cutoff Λ , define an effective potential V_Λ , prove a pertinent flow equation and compare with the corresponding terms in the functional integral formalism. The flow of V_Λ is a version of Wilson’s renormalization group. The restriction of these operators to local interactions can be approximated by a subfamily of the Stückelberg–Petermann renormalization group.

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1. Introduction

There are different versions of the renormalization group (RG), however their relations are not completely understood. The aim of this paper is to clarify the connection between the renormalization groups of Stückelberg–Petermann and Wilson in the framework of perturbation theory. In order for this paper to be better understood for physicists, we use sometimes a graphical language and omit some mathematical technicalities, for a more mathematical formulation we refer to [2].

By the Stückelberg–Petermann RG and Wilson’s RG, we mean the following.

- The *Stückelberg–Petermann RG* \mathcal{R} [16] is the version of the RG as it appears in causal perturbation theory [13, 9, 6, 7, 1, 2]. It relies on the non-uniqueness of the S -matrix \mathbf{S} . Roughly speaking the Main Theorem states that a change $\mathbf{S} \rightarrow \hat{\mathbf{S}}$

of the renormalization prescription can be absorbed in a renormalization of the interaction $V \rightarrow Z(V)$ [13]:

$$\hat{\mathbf{S}}(V) = \mathbf{S}(Z(V)) \quad \forall V \in \mathcal{F}_{\text{loc}}, \quad (1.1)$$

(where \mathcal{F}_{loc} is the space of all local interactions). The Stückelberg–Petermann RG \mathcal{R} is the set of all bijective maps $Z : \mathcal{F}_{\text{loc}} \rightarrow \mathcal{F}_{\text{loc}}$ appearing in this relation when \mathbf{S} and $\hat{\mathbf{S}}$ run through all admissible S -matrices. From the complete statement of the Main Theorem [6, 7] (see Sec. 3.2), it follows that \mathcal{R} is indeed a group; due to (1.1) \mathcal{R} can be interpreted as the group of finite renormalizations of the S -matrix.

- The *RG in the sense of Wilson* usually relies on a functional integral approach, it describes the dependence of the theory on a cutoff Λ , which one introduces to avoid UV-divergences. We imitate this approach in the framework of causal perturbation theory by proceeding as follows [2]: Let p_Λ be a regularized Feynman propagator, which converges (in an appropriate sense) to the Feynman propagator for $\Lambda \rightarrow \infty$. In terms of p_Λ we construct a regularized S -matrix \mathbf{S}_Λ . With that we define the *effective potential* V_Λ at scale Λ as a function of the original interaction V by the condition that the cutoff theory with interaction V_Λ agrees with the exact theory with interaction V , that is

$$\mathbf{S}_\Lambda(V_\Lambda) = \mathbf{S}(V) \quad \text{or explicitly } V_\Lambda := \mathbf{S}_\Lambda^{-1} \circ \mathbf{S}(V). \quad (1.2)$$

Here we assume that \mathbf{S}_Λ is invertible (proved in [2] and Sec. 4). We point out that in general V_Λ is a *nonlocal* interaction.

The problem with this definition is that \mathbf{S} is usually unknown. Therefore, one computes V_Λ by solving *Polchinski's flow equation* [12, 14, 11], which can be derived from the definition (1.2) (see Sec. 5 and [2]) and has the form

$$\frac{d}{d\Lambda} V_\Lambda = F_\Lambda(V_\Lambda \otimes V_\Lambda), \quad (1.3)$$

where F_Λ is linear and explicitly known. Integration of the flow equation yields V_Λ and from that the S -matrix is obtained by $\mathbf{S}(V) = \mathbf{S}_\Lambda(V_\Lambda)$; in practice it is easier to compute

$$\lim_{\Lambda \rightarrow \infty} \mathbf{S}_\Lambda(V_\Lambda), \quad (1.4)$$

since several terms vanish in this limit and, hence, need not be computed in detail.

We point out that there is no group structure in the mathematical sense in Wilson's RG.

2. Star-Product Quantization

We use a formalism which arises when applying deformation quantization to the underlying free classical fields [4, 5].

To simplify the notations, we restrict this paper to a real scalar field φ in d -dimensional Minkowski space. We work with an “off-shell formalism” which means that the classical field configuration space is $C^\infty(\mathbb{R}^d)$ (and not only the space of solutions of the field equations).

We define the space \mathcal{F} of *observables* as the set of all functionals $F : C^\infty(\mathbb{R}^d) \rightarrow \mathbb{C}$, which are infinitely differentiable and all functional derivatives $\frac{\delta^n F}{\delta \varphi^n}$ ($n \in \mathbb{N}$) must be distributions with compact supports. There is an additional defining condition on the wave front sets $\text{WF}(\frac{\delta^n F}{\delta \varphi^n})$, $n \in \mathbb{N}$, which is a microlocal version of translation invariance [4–6, 2].

The following subspaces of \mathcal{F} will be of crucial importance.

- The *nonlocal functionals* \mathcal{F}_0 are defined by the stronger requirement that $\frac{\delta^n F}{\delta \varphi^n}$ is a smooth function with compact support for all $n \in \mathbb{N}$.
- The *local functionals* \mathcal{F}_{loc} are defined by the additional condition that $\frac{\delta^n F}{\delta \varphi^n}(x_1, \dots, x_n) = 0$ if $x_i \neq x_j$ for some (i, j) .

Local interactions are usually of the form

$$F(\varphi) = \int dx f(x) L(\varphi(x), \partial\varphi(x), \partial\partial\varphi(x), \dots) \in \mathcal{F}_{\text{loc}}, \quad (2.1)$$

where $f \in \mathcal{D}(\mathbb{R}^d)$ switches the interaction and $L \in \mathcal{C}^\infty$ does not need to be a polynomial.

By the support of an observable F , we mean $\text{supp } F := \text{supp } \frac{\delta F}{\delta \varphi}$.

The *pointwise product*

$$(F \cdot G)(\varphi) := F(\varphi) \cdot G(\varphi) \quad (2.2)$$

is commutative, we also call it the *classical product*.

To obtain the *Poisson algebra of free fields* we define the Poisson bracket. For this purpose we need the retarded propagator Δ_R of the Klein–Gordon operator, from which we construct the commutator function

$$\Delta(x) := \Delta_R(x) - \Delta_R(-x) = -\Delta(-x). \quad (2.3)$$

Graphically the Poisson bracket of $F, G \in \mathcal{F}$ is defined by contracting once F with G with propagator Δ , i.e.

$$\{F, G\} := \int dx dy \frac{\delta F}{\delta \varphi(x)} \Delta(x - y) \frac{\delta G}{\delta \varphi(y)}. \quad (2.4)$$

In view of a \star -product quantization we introduce $\mathcal{F}[[\hbar]]$ as the space of formal power series in \hbar with coefficients in \mathcal{F} (and similar for subspaces of \mathcal{F}).

Now we define the “*product with propagator p* ”

$$\star_p : \mathcal{F}_1[[\hbar]] \times \mathcal{F}_1[[\hbar]] \rightarrow \mathcal{F}[[\hbar]]; \quad (F, G) \mapsto F \star_p G, \quad (2.5)$$

(where \mathcal{F}_1 is a subspace of \mathcal{F} and $p \in \mathcal{S}'(\mathbb{R}^d)$ is a distribution with suitable properties, see the examples below) by the prescription

$$F \star_p G := \sum_{n \geq 0} \frac{\hbar^n}{n!} \int dx_1 \cdots dy_1 \cdots \frac{\delta^n F}{\delta\varphi(x_1) \cdots \delta\varphi(x_n)} \cdot p(x_1 - y_1) \cdots p(x_n - y_n) \frac{\delta^n G}{\delta\varphi(y_1) \cdots \delta\varphi(y_n)}. \quad (2.6)$$

The zeroth term ($n = 0$) is the classical product. The n th term has precisely n contractions of F with G , each contraction with the propagator p . Hence, $F \star_p G$ is the sum over all possible contractions of F with G . For nonlocal functionals ($\mathcal{F}_1 = \mathcal{F}_0$) the integral in (2.6) exists for all $p \in \mathcal{S}'(\mathbb{R}^d)$ (it means smearing of the distribution $p \otimes \cdots \otimes p$ with the test function $\frac{\delta^n F}{\delta\varphi(x_1) \cdots} \cdot \frac{\delta^n G}{\delta\varphi(y_1) \cdots}$). One can show that \star_p is associative, obviously it is distributive.

The following examples for \star_p are of crucial importance.

- *\star -product quantization.* We choose for p a Hadamard function $H \equiv H_m$. A Hadamard function is a Poincaré invariant solution of the Klein–Gordon equation with mass m , which is smooth in $m \geq 0$ and fulfils

- (i) $H(z) - H(-z) = i\Delta(z)$ and
- (ii) $z \mapsto (H(z) - \Delta_+(z))$ is smooth, where Δ_+ is the Wightman two-point function. Since powers $(\Delta_+(z))^n$ exist, this condition implies that $(H(z))^n$ exists $\forall n \in \mathbb{N}$.

$F \star_H G$ exists also for local functionals, i.e. it exists $\forall F, G \in \mathcal{F}$. Namely, property (ii) and the wave front set property of $\frac{\delta^n F}{\delta\varphi^n}$ and $\frac{\delta^n G}{\delta\varphi^n}$ imply that the appearing products of distributions exist [4].

The product \star_H viewed as a map $\mathcal{F} \times \mathcal{F} \rightarrow \mathcal{F}[[\hbar]]$ (i.e. the arguments are $\sim \hbar^0$) is a \star -product, i.e. $F \star_H G$ is a \hbar -dependent deformation of $F \cdot G$,

$$\lim_{\hbar \rightarrow 0} F \star_H G = F \cdot G, \quad (2.7)$$

with

$$\lim_{\hbar \rightarrow 0} \frac{1}{i\hbar} (F \star_H G - G \star_H F) = \{F, G\}. \quad (2.8)$$

The validity of the last relation relies on property (i) of H . The Wightman two-point function Δ_+ yields also a \star -product \star_{Δ_+} , but Δ_+ is not smooth in m at $m = 0$.

- *Time-ordered product of nonlocal functionals.* The time-ordered product with respect to the \star -product \star_H must satisfy

$$T(\varphi(x)\varphi(y)) := \begin{cases} \varphi(x) \star_H \varphi(y) & \text{if } x^0 > y^0, \\ \varphi(y) \star_H \varphi(x) & \text{if } y^0 > x^0. \end{cases} \quad (2.9)$$

These two cases can be summarized as

$$T(\varphi(x)\varphi(y)) = \varphi(x) \star_{H_F} \varphi(y) \quad (2.10)$$

with

$$H_F(z) := \Theta(z^0)H(z) + \Theta(-z^0)H(-z) (= H_F(-z)). \quad (2.11)$$

Hence, the propagator for the time-ordered product w.r.t. \star_H is H_F and, therefore, we define the time-ordered product of *nonlocal* functionals as the product with propagator H_F :

$$T(F_1 \otimes \cdots \otimes F_n) := F_1 \star_{H_F} \cdots \star_{H_F} F_n, \quad \forall F_1, \dots, F_n \in \mathcal{F}_0. \quad (2.12)$$

Since $H_F(-z) = H_F(z)$, this time-ordered product is commutative, hence it cannot be a \star -product (due to (2.8)).

3. The Stückelberg–Petermann Renormalization Group

3.1. Time-ordered product of local functionals

For simplicity we assume from now on that all observables $F \in \mathcal{F}$ are polynomial in φ and its derivatives, and we write \mathcal{F} for $\mathcal{F}[[\hbar]]$ (and similar for subspaces of \mathcal{F}).

Trying to extend the definition (2.12) to local functionals, powers $(H_F(z))^n$ and terms like $H_F(z_1)H_F(z_2)H_F(z_1 + z_2)$ appear, which do not exist in $d \geq 4$ or $d \geq 6$ dimensions! (These are the famous UV-divergences of perturbative QFT.) Therefore, we define the time-ordered product of local functionals in an alternative, axiomatic way: we require that the time-ordered product of n th order

$$T_n : \mathcal{F}_{\text{loc}}^{\otimes n} \rightarrow \mathcal{F} \quad (3.1)$$

is a linear and totally symmetric map. With that the defining axioms can be given in terms of the generating functional – the S -matrix

$$\mathbf{S} : \mathcal{F}_{\text{loc}} \rightarrow \mathcal{F}; \quad \mathbf{S}(V) := \sum_{n=0}^{\infty} \frac{T_n(V^{\otimes n})}{n!}. \quad (3.2)$$

Or vice versa, T_n is obtained from \mathbf{S} by

$$T_n(V^{\otimes n}) = \mathbf{S}^{(n)}(0)(V^{\otimes n}) \equiv \frac{d^n}{d\lambda^n} \mathbf{S}(\lambda V)|_{\lambda=0} \quad (3.3)$$

(where $\mathbf{S}^{(n)}(0)$ denotes the n th derivative of \mathbf{S} at the origin). We use the axioms of causal perturbation theory [8, 15, 3]^a

Causality: $\mathbf{S}(A + B) = \mathbf{S}(A) \star_{H_m} \mathbf{S}(B)$ if $\text{supp } A$ is later than $\text{supp } B$, i.e. $\text{supp } A \cap (\text{supp } B + \bar{V}_-) = \emptyset$ (where \bar{V}_- denotes the full and closed backward light cone).

Starting element: $\mathbf{S}(0) = 1$, $\mathbf{S}^{(1)}(0) = \text{id}$.

^aIn view of the generalization to curved spacetimes we work with a somewhat modified version of the axioms given in [6].

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Field independence: $\delta\mathbf{S}/\delta\varphi = 0$.

Poincaré invariance

Unitarity: $\overline{\mathbf{S}(-V)} \star_{H_m} \mathbf{S}(\overline{V}) = 1$ (where the bar means complex conjugation).

Smoothness in m : \mathbf{S} depends smoothly on the mass m of the free theory $\forall m \geq 0$.

Scaling: \mathbf{S} scales almost homogeneously under $(x, m) \mapsto (\rho x, \rho^{-1}m)$, by which we mean that homogeneous scaling (holding for the corresponding classical theory) is maintained up to powers of $\log \rho$.

Note that in the causality condition the \star -product w.r.t. a Hadamard function H_m appears. It is here where the information about the free field equation (in particular about the value of the mass $m \geq 0$) enters the axioms. If H would be replaced by Δ_+ , smoothness in m would be violated at $m = 0$.

Epstein and Glaser showed that these axioms have a solution [8] (for somewhat alternative proofs see [15, 3, 6]): they gave a construction of the time-ordered products T_n by induction on n . In this construction renormalization appears as the problem of extending the distributional kernels of T_n from $\mathcal{D}(\mathbb{R}^{dn} \setminus \Delta_n)$ to $\mathcal{D}(\mathbb{R}^{dn})$ where $\Delta_n := \{(x_1, \dots, x_n) \in \mathbb{R}^{dn} \mid x_1 = x_2 = \dots = x_n\}$. The non-uniqueness of this extension is the reason for the non-uniqueness of the S -matrix.

“Causality” and “starting element” are the basic axioms; the other axioms are not mandatory, they are called (re)normalization conditions because their only purpose is to restrict the set of admissible extensions.

3.2. Non-uniqueness of the S -matrix

We define the *Stückelberg–Petermann RG* \mathcal{R} as the set of all analytic bijections $Z: \mathcal{F}_{\text{loc}} \rightarrow \mathcal{F}_{\text{loc}}$ with

Starting element: $Z(0) = 0$, $Z^{(1)}(0) = \text{id}$, $Z = \text{id} + O(\hbar)$.

Locality: Z is local in the sense that

$$Z(A + B + C) = Z(A + B) - Z(B) + Z(B + C)$$

if $\text{supp } A \cap \text{supp } C = \emptyset$.

Field independence: $\delta Z/\delta\varphi = 0$.

Poincaré invariance

Unitarity: $\overline{Z}(-V) + Z(V) = 0$.

Smoothness in m : Z depends smoothly on $m \geq 0$.

Scaling: Z scales almost homogeneously under $(x, m) \mapsto (\rho x, \rho^{-1}m)$.

Every renormalization condition on \mathbf{S} has a corresponding requirement on Z . Analyticity of Z means that it is given by its Taylor series:

$$Z(V) = \sum_{n=1}^{\infty} \frac{Z^{(n)}(0)(V^{\otimes n})}{n!}. \quad (3.4)$$

The “Main Theorem” describes the non-uniqueness of the S -matrix in terms of the Stückelberg–Petermann RG \mathcal{R} .

Theorem 1. (i) *Given two renormalization prescriptions \mathbf{S} and $\hat{\mathbf{S}}$, there exists a unique map $Z : \mathcal{F}_{\text{loc}} \rightarrow \mathcal{F}_{\text{loc}}$ with $Z(0) = 0$ and*

$$\hat{\mathbf{S}} = \mathbf{S} \circ Z. \quad (3.5)$$

This Z is an element of the Stückelberg–Petermann RG \mathcal{R} .

(ii) *Conversely, given an S -matrix \mathbf{S} and an arbitrary $Z \in \mathcal{R}$, then $\hat{\mathbf{S}} := \mathbf{S} \circ Z$ also satisfies the axioms for an S -matrix.*

For the proof we refer to [6].

A corollary of this theorem states that, for $Z_1, Z_2 \in \mathcal{R}$, the composition $Z_1 \circ Z_2$ is also an element of \mathcal{R} , i.e. that \mathcal{R} is indeed a *group* [6]. Namely, given $Z_1, Z_2 \in \mathcal{R}$ and choosing an arbitrary S -matrix \mathbf{S} , part (ii) implies that $\mathbf{S}_1 := \mathbf{S} \circ Z_1$ and $\mathbf{S}_2 := \mathbf{S}_1 \circ Z_2$ also satisfy the axioms. From $\mathbf{S}_2 = \mathbf{S} \circ (Z_1 \circ Z_2)$ and part (i) it follows that $Z_1 \circ Z_2 \in \mathcal{R}$.

4. Regularized Time-Ordered Product

The definition (2.12) of the time-ordered product of nonlocal functionals can be extended to local functionals, if one regularizes the Feynman propagator H_F by introducing a cutoff Λ .

Let $(p_\Lambda)_{\Lambda>0}$ be a family of *test functions* ($p_\Lambda \in \mathcal{S}(\mathbb{R}^d)$) which approximates H_F , more precisely

$$\lim_{\Lambda \rightarrow \infty} p_\Lambda = H_F \quad \text{in the Hörmander topology [10],}$$

and for $\Lambda \rightarrow 0$ it is required that

$$p_0 = 0 \quad \text{or} \quad \lim_{\Lambda \rightarrow 0} p_\Lambda = 0 \quad \text{in the Hörmander topology.}$$

With regard to $H_F(-z) = H_F(z)$, we additionally require $p_\Lambda(-z) = p_\Lambda(z)$.

The regularized time-ordered product,

$$T_\Lambda(F^{\otimes n}) := F \star_{p_\Lambda} \cdots \star_{p_\Lambda} F \quad (4.1)$$

is well-defined $\forall F \in \mathcal{F}$ since $p_\Lambda \in \mathcal{S}(\mathbb{R}^d)$.

The corresponding generating functional is the regularized S -matrix

$$\mathbf{S}_\Lambda : \mathcal{F} \rightarrow \mathcal{F}; \quad \mathbf{S}_\Lambda(F) := \sum_{n=0}^{\infty} \frac{1}{n!} T_\Lambda(F^{\otimes n}) =: e_{\star_{p_\Lambda}}^F. \quad (4.2)$$

(The last expression is a suggestive short-hand notation for the series.) In contrast to the exact S -matrix \mathbf{S} , the domain of \mathbf{S}_Λ is \mathcal{F} (and not only \mathcal{F}_{loc}) and \mathbf{S}_Λ is invertible. We also point out that $\lim_{\Lambda \rightarrow \infty} \mathbf{S}_\Lambda$ does not exist in general.

Proof of invertability. Following [2], we write the product \star_{p_Λ} alternatively as

$$F \star_{p_\Lambda} G = \tau_\Lambda (\tau_\Lambda^{-1} F \cdot \tau_\Lambda^{-1} G), \quad (4.3)$$

where

$$\tau_\Lambda F := \exp(i\hbar\Gamma_\Lambda) F \quad (4.4)$$

with

$$\Gamma_\Lambda := \frac{1}{2} \int dx dy p_\Lambda(x-y) \frac{\delta^2}{\delta\varphi(x)\delta\varphi(y)}. \quad (4.5)$$

Graphically $(\tau_\Lambda F)(\varphi)$ is the sum over all possible contractions (with propagator p_Λ) of φ in $F(\varphi)$. Obviously, the inverse operator τ_Λ^{-1} is $\tau_\Lambda^{-1} = \exp(-i\hbar\Gamma_\Lambda)$. Note that the operators τ_Λ^{-1} in (4.3) are needed to remove the tadpole diagrams.

With (4.3), \mathbf{S}_Λ can be written as

$$\mathbf{S}_\Lambda = \tau_\Lambda \circ \exp \circ \tau_\Lambda^{-1} \quad (4.6)$$

(where $\exp F = 1 + F + F \cdot F/2! + \dots$) from which it is obvious that \mathbf{S}_Λ is invertible:

$$\mathbf{S}_\Lambda^{-1} = \tau_\Lambda \circ \log \circ \tau_\Lambda^{-1}. \quad (4.7)$$

□

Examples for regularized (Feynman) propagators:

- *Euclidean theory with mass $m > 0$* (following [14]).

Let $K \in \mathcal{C}^\infty(\mathbb{R}_0^+, [0, 1])$ with

$$K(x) = \begin{cases} 0 & \text{if } x \geq 4 \\ 1 & \text{if } x \leq 1 \end{cases}$$

and $K'(x) < 0 \forall x \in (1, 4)$, i.e. K is a smooth version of a step function. The Euclidean propagator is regularized by cutting off the momenta above a scale Λ :

$$\hat{p}_\Lambda(k) := \frac{1}{(2\pi)^2 (k^2 + m^2)} K\left(\frac{k^2}{\Lambda^2}\right) \in \mathcal{S}(\mathbb{R}^d) \quad (k^2 \equiv k_0^2 + \mathbf{k}^2). \quad (4.8)$$

It follows that $p_\Lambda(x) \in \mathcal{S}(\mathbb{R}^d)$, $p_\Lambda(-x) = p_\Lambda(x)$ and that

$$\lim_{\Lambda \rightarrow \infty} \hat{p}_\Lambda(k) = \frac{1}{(2\pi)^2 (k^2 + m^2)} \quad (= \text{Eucl. prop.}), \quad \lim_{\Lambda \rightarrow 0} \hat{p}_\Lambda(k) = 0 \quad (4.9)$$

w.r.t. the weak topology of $\mathcal{S}'(\mathbb{R}^d)$. Due to the continuity of the inverse Fourier transformation from $\mathcal{S}'(\mathbb{R}^d)$ to $\mathcal{S}'(\mathbb{R}^d)$, these convergence statements hold also in x -space w.r.t. the weak topology. They are valid also w.r.t. the Hörmander topology in x -space. For the Euclidean propagator $p(x) := \lim_{\Lambda \rightarrow \infty} p_\Lambda(x)$, one obtains

$$p(x) = \frac{2\pi^{\frac{d+1}{2}}}{\Gamma(\frac{d-1}{2})} \int_m^\infty dq (q^2 - m^2)^{\frac{d-3}{2}} e^{-q|x|} \in \mathcal{S}'(\mathbb{R}^d),$$

where $|x| \equiv \sqrt{x_0^2 + \mathbf{x}^2}$. In low dimensions the remaining integral gives

$$d = 2 : p(x) = 2\pi K_0(m|x|)$$

(where K_0 is a modified Bessel function of the second kind) and

$$d = 3 : p(x) = 2\pi^2 \frac{e^{-m|x|}}{|x|}.$$

Both expressions have an integrable singularity at $x = 0$ and decay exponentially for $|x| \rightarrow \infty$.

- ϵ -regularized relativistic theory with $m > 0$ (following [11]).

ϵ -regularization of the relativistic theory means that the Minkowski metric is replaced by $i\eta_\epsilon$, where

$$k\eta_\epsilon k := k_0^2(\epsilon - i) + \mathbf{k}^2(\epsilon + i) \quad \text{with } \epsilon > 0.$$

Note that $k\eta_\epsilon k \neq 0$ for $k \neq 0$ and that

$$\text{Re}(k\eta_\epsilon k + (\epsilon + i)m^2) = \epsilon(k_0^2 + \mathbf{k}^2 + m^2) \geq \epsilon m^2 \quad \forall k. \quad (4.10)$$

For the Feynman propagator of the ϵ -regularized relativistic theory,

$$\hat{p}_\epsilon(k) = \frac{i}{(2\pi)^2 (k\eta_\epsilon k + (\epsilon + i)m^2)},$$

an UV-cutoff Λ is introduced by an exponential damping:

$$\hat{p}_{\epsilon,\Lambda}(k) := e^{-\Lambda^{-1}(k\eta_\epsilon k + (\epsilon + i)m^2)} \hat{p}_\epsilon(k) = \frac{i}{(2\pi)^2} \int_{\Lambda^{-1}}^\infty d\alpha e^{-\alpha(k\eta_\epsilon k + (\epsilon + i)m^2)} \quad (4.11)$$

Obviously $\hat{p}_{\epsilon,\Lambda}(k) \in \mathcal{S}(\mathbb{R}^d)$ holds and hence $p_{\epsilon,\Lambda}(x) \in \mathcal{S}(\mathbb{R}^d)$. We also see that $p_{\epsilon,\Lambda}(-x) = p_{\epsilon,\Lambda}(x)$.

For fixed $\epsilon > 0$ we find

$$\lim_{\Lambda \rightarrow \infty} p_{\epsilon,\Lambda}(x) = p_\epsilon(x) \quad \text{and} \quad \lim_{\Lambda \rightarrow 0} p_{\epsilon,\Lambda}(x) = 0$$

w.r.t. the weak topology of $\mathcal{S}'(\mathbb{R}^d)$ and also w.r.t. the Hörmander topology. Namely, for $\Lambda \rightarrow \infty$ the convergence behavior is essentially similar to the Euclidean case treated above (due to (4.10)) and for $\Lambda \rightarrow 0$ the behavior of $p_{\epsilon,\Lambda}(x)$ is dominated by a prefactor $e^{-\Lambda^{-1}\epsilon m^2}$.

For $\epsilon \downarrow 0$ the family $(\hat{p}_\epsilon(k))_{\epsilon>0}$ of analytic functions converges to the distribution

$$\lim_{\epsilon \downarrow 0} \hat{p}_\epsilon(k) = \frac{1}{(2\pi)^2 (m^2 - k^2 - i0)} \quad (= \text{Feynman propagator}),$$

w.r.t. the weak topology of $\mathcal{S}'(\mathbb{R}^d)$ and, hence, this holds also in x -space: $\lim_{\epsilon \downarrow 0} p_\epsilon(x) = (\text{Feynman propagator})$ in $\mathcal{S}'(\mathbb{R}^d)$. Whether this holds also w.r.t. the Hörmander topology is a more difficult question, which cannot be answered with the mathematical tools explained in this paper.

In both examples the propagator

$$p_{\Lambda, \Lambda_0} := p_{\Lambda_0} - p_\Lambda \quad (0 < \Lambda \leq \Lambda_0 < \infty) \quad (4.12)$$

has an UV-cutoff ($\Lambda_0 \rightarrow \infty$) and an IR-cutoff ($\Lambda \rightarrow 0$).

5. Effective Potential and Flow Equation

To define the effective potential V_Λ , we recall that \mathbf{S}_Λ is explicitly known and invertible and that \mathbf{S} exists (although it is usually unknown). With that the effective potential V_Λ at scale Λ can be defined as explained in the introduction:

$$V_\Lambda := \mathbf{S}_\Lambda^{-1} \circ \mathbf{S}(V). \quad (5.1)$$

We also recall that in general $V_\Lambda \notin \mathcal{F}_{\text{loc}}$.

Similarly to $\mathbf{S}(V)$, V_Λ can be viewed as a formal power series in \hbar , or in V , or in both. For the lowest terms of the expansion in V we obtain

$$V_\Lambda = V + \mathcal{O}(V^2), \quad (5.2)$$

by using the axiom Starting element and (4.7).

In particular, for $\Lambda = 0$ we obtain

$$V_0 = \log \circ \mathbf{S}(V) \quad (5.3)$$

(due to $\mathbf{S}_0(V) = e^V \equiv \sum_n \frac{V \cdots V}{n!}$).

Flow operator. From the definition (5.1) it follows

$$V_\Lambda = \mathbf{S}_\Lambda^{-1} \circ \mathbf{S}_{\Lambda_0}(V_{\Lambda_0}), \quad (5.4)$$

i.e. $\mathbf{S}_\Lambda^{-1} \circ \mathbf{S}_{\Lambda_0}$ is the “flow of the effective potential from Λ_0 to Λ ”.

We want to clarify the relation between this flow operator and $\mathbf{S}_{\Lambda, \Lambda_0}$; by the latter we mean the regularized S -matrix with propagator p_{Λ, Λ_0} (4.12), analogously to (4.1) and (4.2). Similarly to (4.6), $\mathbf{S}_{\Lambda, \Lambda_0}$ satisfies

$$\mathbf{S}_{\Lambda, \Lambda_0} = \tau_{\Lambda, \Lambda_0} \circ \exp \circ \tau_{\Lambda, \Lambda_0}^{-1}, \quad (5.5)$$

where $\tau_{\Lambda, \Lambda_0}$ is defined as τ_{Λ} (4.4), with propagator p_{Λ, Λ_0} instead of p_{Λ} . For $\Lambda = 0$ we have $p_0 = 0$, $p_{0, \Lambda_0} = p_{\Lambda_0}$, hence $\tau_0 = \text{id}$, $S_0^{-1} = \log$ and $S_{0, \Lambda_0} = S_{\Lambda_0}$. With that, $\mathbf{S}_0^{-1} \circ \mathbf{S}_{\Lambda_0}$ (i.e. the flow from Λ_0 to 0) is equal to $\log \circ \mathbf{S}_{0, \Lambda_0}$. For the flow from Λ_0 to an arbitrary $\Lambda \in [0, \Lambda_0]$ we assert

$$\mathbf{S}_{\Lambda}^{-1} \circ \mathbf{S}_{\Lambda_0} = \tau_{\Lambda} \circ \log \circ \mathbf{S}_{\Lambda, \Lambda_0} \circ \tau_{\Lambda}^{-1}. \quad (5.6)$$

Proof. We first note that

$$\tau_{\Lambda, \Lambda_0} = \exp(i\hbar(\Gamma_{\Lambda_0} - \Gamma_{\Lambda})) = \tau_{\Lambda}^{-1} \circ \tau_{\Lambda_0} = \tau_{\Lambda_0} \circ \tau_{\Lambda}^{-1}.$$

Due to (4.6) and (5.5) it holds

$$\mathbf{S}_{\Lambda, \Lambda_0} = \tau_{\Lambda, \Lambda_0} \circ \exp \circ \tau_{\Lambda, \Lambda_0}^{-1} = \tau_{\Lambda}^{-1} \circ \mathbf{S}_{\Lambda_0} \circ \tau_{\Lambda} \quad (5.7)$$

and with that we obtain

$$\mathbf{S}_{\Lambda}^{-1} \circ \mathbf{S}_{\Lambda_0} \circ \tau_{\Lambda} = \tau_{\Lambda} \circ \log \circ \tau_{\Lambda}^{-1} \circ \mathbf{S}_{\Lambda_0} \circ \tau_{\Lambda} = \tau_{\Lambda} \circ \log \circ \mathbf{S}_{\Lambda, \Lambda_0}. \quad \square$$

Flow equation. The flow equation (cf. [12, 14, 11, 2]) is a differential equation for V_{Λ} as a function of Λ .

Theorem 2.

$$\frac{d}{d\Lambda} V_{\Lambda} = -\frac{\hbar}{2} \int dx dy \frac{dp_{\Lambda}(x-y)}{d\Lambda} \frac{\delta V_{\Lambda}}{\delta \varphi(x)} \star_{p_{\Lambda}} \frac{\delta V_{\Lambda}}{\delta \varphi(y)} \quad (5.8)$$

$$= -\frac{1}{2} \frac{d}{d\lambda} \Big|_{\lambda=\Lambda} (V_{\Lambda} \star_{p_{\lambda}} V_{\Lambda}). \quad (5.9)$$

Proof.^b From $\mathbf{S}_{\Lambda}(V) = e^{\star_{p_{\Lambda}} V}$, we see that

$$\frac{d}{d\lambda} \mathbf{S}_{\Lambda}(V_{\lambda}) = \frac{dV_{\lambda}}{d\lambda} \star_{p_{\Lambda}} \mathbf{S}_{\Lambda}(V_{\lambda})$$

and with that we obtain

$$0 = \frac{d}{d\Lambda} \mathbf{S}_{\Lambda}(V_{\Lambda}) = \frac{d}{d\lambda} \Big|_{\lambda=\Lambda} \mathbf{S}_{\lambda}(V_{\Lambda}) + \frac{dV_{\Lambda}}{d\Lambda} \star_{p_{\Lambda}} \mathbf{S}_{\Lambda}(V_{\Lambda}).$$

Due to $\mathbf{S}_{\Lambda}(F) = 1 + \mathcal{O}(F)$ the inverse (w.r.t. $\star_{p_{\Lambda}}$) regularized S -matrix $\mathbf{S}_{\Lambda}(F)^{-1}$ exists. With that it follows that

$$\frac{dV_{\Lambda}}{d\Lambda} = -\frac{d}{d\lambda} \Big|_{\lambda=\Lambda} \mathbf{S}_{\lambda}(V_{\Lambda}) \star_{p_{\Lambda}} \mathbf{S}_{\Lambda}(V_{\Lambda})^{-1}. \quad (5.10)$$

^bA somewhat different proof is given in [2].

From the definition (2.6) of \star_p we obtain

$$\frac{d}{d\Lambda} \frac{F \star_{p_\Lambda} F}{2} = \frac{\hbar}{2} \int dx dy \frac{dp_\Lambda(x-y)}{d\Lambda} \frac{\delta F}{\delta\varphi(x)} \star_{p_\Lambda} \frac{\delta F}{\delta\varphi(y)} \quad (5.11)$$

and for n factors

$$\frac{d}{d\Lambda} \frac{T_\Lambda(F^{\otimes n})}{n!} = \frac{\hbar}{2(n-2)!} \int dx dy \frac{dp_\Lambda(x-y)}{d\Lambda} \frac{\delta F}{\delta\varphi(x)} \star_{p_\Lambda} \frac{\delta F}{\delta\varphi(y)} \star_{p_\Lambda} \star_{p_\Lambda} F \star_{p_\Lambda} \cdots \star_{p_\Lambda} F$$

(two factors $\frac{\delta F}{\delta\varphi}$ and $(n-2)$ factors F). Summing over n we obtain

$$\frac{d}{d\Lambda} \mathbf{S}_\Lambda(F) = \frac{\hbar}{2} \int dx dy \frac{dp_\Lambda(x-y)}{d\Lambda} \frac{\delta F}{\delta\varphi(x)} \star_{p_\Lambda} \frac{\delta F}{\delta\varphi(y)} \star_{p_\Lambda} \mathbf{S}_\Lambda(F). \quad (5.12)$$

Inserting this into (5.10) it results (5.8), from which we obtain (5.9) by using (5.11). \square

Construction of V_Λ . Usually \mathbf{S} is unknown, only V and $(p_\Lambda)_{\Lambda>0}$ are given, and from that V_Λ is computed by solving the flow equation. In perturbation theory this amounts to an inductive construction of V_Λ as a formal power series in V . Namely, denoting by $V_\Lambda^{(n)}$ the term in V_Λ of order n in V , and taking $V_\Lambda^{(0)} = 0$ into account, the perturbative version of the flow equation reads

$$\frac{d}{d\Lambda} V_\Lambda^{(n)} = \sum_{k=1}^{n-1} -\frac{1}{2} \frac{d}{d\lambda} \Big|_{\lambda=\Lambda} (V_\Lambda^{(k)} \star_{p_\Lambda} V_\Lambda^{(n-k)}). \quad (5.13)$$

Proceeding inductively, we start with $V_\Lambda^{(1)} = V$ (5.2) and assume that $V_\Lambda^{(k)}$ is known for all $k < n$. Then, the R.H.S. is known and, hence, an integration yields $V_\Lambda^{(n)}$. A major problem is the determination of the integration constant by a suitable boundary value. (The value (5.3) at $\Lambda = 0$ does not help, because it contains the unknown \mathbf{S} .) We refer to the usual procedure which is roughly sketched in the next section.

Concerning the removal of the cutoff Λ , we point out that V_Λ diverges in general for $\Lambda \rightarrow \infty$. But $\lim_{\Lambda \rightarrow \infty} \mathbf{S}_\Lambda(V_\Lambda)$ exists and gives $\mathbf{S}(V)$.

6. Comparison with the Functional Integral Approach

First we roughly sketch the usual procedure for the Euclidean theory, following [14]. One defines an effective action G_{Λ, Λ_0} by the functional integral

$$e^{G_{\Lambda, \Lambda_0}(\varphi)} := \int d\mu_{p_{\Lambda, \Lambda_0}}(\phi) e^{-\lambda V^{(\Lambda_0)}(\phi + \varphi)}, \quad (6.1)$$

where the normalization of the functional integral is included in the Gaussian measure $d\mu_{p_{\Lambda, \Lambda_0}}$, the covariance p_{Λ, Λ_0} of $d\mu_{p_{\Lambda, \Lambda_0}}$ is given by (4.12), λ is the coupling constant and $V^{(\Lambda_0)}$ is the interaction. Heuristically speaking, the “degrees of freedom

in the region $\Lambda^2 \prec k^2 \prec \Lambda_0^2$ are integrated out” where k is the momentum. Graphically $G_{\Lambda, \Lambda_0}(\varphi)$ is the sum of all connected Feynman diagrams with vertices $\lambda V^{(\Lambda_0)}$, internal lines symbolizing p_{Λ, Λ_0} and external lines symbolizing the field φ .

The interaction $V^{(\Lambda_0)}$ is usually local and depends on Λ_0 since it is normally ordered with respect to p_{0, Λ_0} (or p_{Λ, Λ_0}) and because it contains Λ_0 -dependent local counterterms as explained in (6.2), (6.3) below.

A main difference to our formalism is that there the interaction V has compact support (see (2.1)); but this does not hold here, e.g. for the φ^n -model the unrenormalized interaction (i.e. without counterterms) reads

$$\int d^d x \Omega_p((\varphi(x))^n), \quad \text{where } \Omega_p(\cdots) \text{ denotes normal ordering w.r.t. } p.$$

Therefore, in our formalism IR-divergences do not occur; but here they can appear and, hence, in general it is necessary to introduce the IR-cutoff $\Lambda > 0$. Purely massive models are an exception: they are IR-finite also in the usual formalism and, hence, one can set $\Lambda = 0$.

Computing $\frac{\partial}{\partial \Lambda}$ of the functional integral (6.1) one derives the flow equation. Let $G_{\Lambda, \Lambda_0}^{(r)}$ be that term of G_{Λ, Λ_0} which is of order r in the coupling constant λ (or equivalently in V). Proceeding by induction on r , the flow equation expresses $\frac{\partial G_{\Lambda, \Lambda_0}^{(r)}}{\partial \Lambda}$ in terms of lower order terms $G_{\Lambda, \Lambda_0}^{(k)}$, $k < r$, which are inductively known. Solving the flow equation

$$G_{\Lambda, \Lambda_0}^{(r)} = G_{\Lambda_0, \Lambda_0}^{(r)} - \int_{\Lambda}^{\Lambda_0} d\Lambda' \frac{\partial G_{\Lambda', \Lambda_0}^{(r)}}{\partial \Lambda'}$$

(where $\frac{\partial G_{\Lambda', \Lambda_0}^{(r)}}{\partial \Lambda'}$ is expressed in terms of inductively known terms by the flow equation) there appears the crucial question how to choose the boundary value G_{Λ_0, Λ_0} . Choosing for G_{Λ_0, Λ_0} the unrenormalized (normally ordered) interaction $-\lambda \Omega_p(V)$, the limit $\lim_{\Lambda_0 \rightarrow \infty} G_{\Lambda, \Lambda_0}$ does not exist in general (due to the usual UV-divergences). Therefore, one adds Λ_0 -dependent local counterterms,

$$G_{\Lambda_0, \Lambda_0} = -\lambda V^{(\Lambda_0)} = -\lambda \Omega_p(V) + \Lambda_0\text{-dependent local counterterms}, \quad (6.2)$$

such that this limit exists. The theory is “perturbatively renormalizable” if this is possible by a *finite* number of counterterms (each counterterm may be a formal power series in λ). In case of the ϕ^4 -interaction in $d = 4$ dimensions one has to add three counterterms of the form

$$\begin{aligned} G_{\Lambda_0, \Lambda_0} = \lambda \Omega_p(\phi^4) & \left(-1 + \sum_{r \geq 1} c_{\Lambda_0, r} \lambda^r \right) \\ & + \Omega_p(\phi^2) \sum_{r \geq 2} a_{\Lambda_0, r} \lambda^r + \Omega_p((\partial\phi)^2) \sum_{r \geq 2} b_{\Lambda_0, r} \lambda^r, \end{aligned} \quad (6.3)$$

where $a_{\Lambda_0, r}$, $b_{\Lambda_0, r}$, $c_{\Lambda_0, r}$ are Λ_0 -dependent numbers.

We now compare with our formalism.

- $\tau_{\Lambda, \Lambda_0}$ and $\mathbf{S}_{\Lambda, \Lambda_0}$ as functional integrals: For $F \in \mathcal{F}$

$$(\tau_{\Lambda, \Lambda_0} F)(\varphi) \quad \text{corresponds to} \quad \int d\mu_{p_{\Lambda, \Lambda_0}}(\phi) F(\phi + \varphi), \quad (6.4)$$

since both expressions are the sum over all possible contractions of φ in $F(\varphi)$ with propagator p_{Λ, Λ_0} .

Moreover, let $\mathbf{S}_{\Lambda, \Lambda_0}$ be the regularized S -matrix with propagator p_{Λ, Λ_0} . Then, for $V \in \mathcal{F}$,

$$S_{\Lambda, \Lambda_0}(\lambda V)(\varphi) \quad \text{corresponds to} \quad \int d\mu_{p_{\Lambda, \Lambda_0}}(\phi) e^{-\lambda \Omega_{p_{\Lambda, \Lambda_0}}(V(\phi + \varphi))}, \quad (6.5)$$

since for both expressions the term $\sim \lambda^n$ is the sum over all contractions (with propagator p_{Λ, Λ_0}) between n vertices, each vertex given by V . Note that in the functional integral, self-contractions of a vertex (i.e. tadpoles) drop out due to the normal ordering of V w.r.t. p_{Λ, Λ_0} .

Even for $F, V \in \mathcal{F}_{\text{loc}}$ all expressions in (6.4) and (6.5) are well-defined (i.e. renormalization is not needed at this level) since $p_{\Lambda, \Lambda_0} \in \mathcal{S}(\mathbb{R}^d)$.

- *Effective potential*: Our effective potential

$$V_\Lambda := \mathbf{S}_\Lambda^{-1} \circ \mathbf{S}(V) \quad \text{corresponds roughly to} \quad G_{\Lambda, \infty} := \lim_{\Lambda_0 \rightarrow \infty} G_{\Lambda, \Lambda_0}. \quad (6.6)$$

For $\Lambda = 0$ these expressions agree: namely in our formalism we have the value

$$e^{V_0(\varphi)} = \mathbf{S}(V)(\varphi) \quad (6.7)$$

(see (5.3)), which is a main justification to interpret V_Λ as effective potential. On the other hand, in an IR-finite model, the functional integral

$$\lim_{\Lambda_0 \rightarrow \infty} e^{G_{0, \Lambda_0}(\varphi)} = \lim_{\Lambda_0 \rightarrow \infty} \int d\mu_{p_{0, \Lambda_0}}(\phi) e^{-\lambda V^{(\Lambda_0)}(\phi + \varphi)} \quad (6.8)$$

gives also $\mathbf{S}(V)(\varphi)$.

As mentioned above, the existence of $\lim_{\Lambda_0 \rightarrow \infty} G_{\Lambda, \Lambda_0}$ involves renormalization that is the addition of suitable local counterterms. Also the definition (1.2) of V_Λ presupposes renormalization, since V_Λ is defined in terms of the renormalized S -matrix.

- *UV-finite models*: In an UV-finite theory (e.g. interaction ϕ^n in $d = 2$ dimensions or ϕ^2 for $d = 3$) $V^{(\Lambda_0)}$ (6.2) depends on Λ_0 only by normal ordering. If the latter is done with respect to p_{Λ, Λ_0} , we see from (6.1) and (6.5) that

$$S_{\Lambda, \Lambda_0}(\lambda V)(\varphi) \quad \text{corresponds to} \quad e^{G_{\Lambda, \Lambda_0}(\varphi)}. \quad (6.9)$$

Taking also

$$\mathbf{S}(F) = \lim_{\Lambda_0 \rightarrow \infty} \mathbf{S}_{\Lambda_0}(F), \quad \forall F \in \mathcal{F}_{\text{loc}}, \quad (6.10)$$

(see (6.14) below) and (5.7) into account and choosing $\lambda = 1$ we obtain

$$\begin{aligned} G_{\Lambda, \infty} &\simeq \lim_{\Lambda_0 \rightarrow \infty} \log \circ \mathbf{S}_{\Lambda, \Lambda_0}(V) \\ &= \lim_{\Lambda_0 \rightarrow \infty} \log \circ \tau_{\Lambda}^{-1} \circ \mathbf{S}_{\Lambda_0} \circ \tau_{\Lambda}(V) = \log \circ \tau_{\Lambda}^{-1} \circ \mathbf{S} \circ \tau_{\Lambda}(V). \end{aligned} \quad (6.11)$$

Usually this differs from

$$V_{\Lambda} = \mathbf{S}_{\Lambda}^{-1} \circ \mathbf{S}(V) = \tau_{\Lambda} \circ \log \circ \tau_{\Lambda}^{-1} \circ \mathbf{S}(V); \quad (6.12)$$

an exception is $\Lambda = 0$ (as generally noted in (6.7), (6.8)). Or, arguing somewhat differently: the difference between V_{Λ} (6.12) and $G_{\Lambda, \infty}$ (6.11) amounts to the difference between $\mathbf{S}_{\Lambda}^{-1} \circ \mathbf{S}_{\Lambda_0}$ and $\log \circ \mathbf{S}_{\Lambda, \Lambda_0}$ for $\Lambda_0 \rightarrow \infty$, which is given by (5.6). The maps $V \mapsto V_{\Lambda}$ (6.12) and $V \mapsto G_{\Lambda, \infty}$ (6.11) agree up to a similarity transformation by τ_{Λ} , which is a matter of convention.

Relation of Wilson's RG to the Stückelberg–Petermann RG (heuristic treatment). The difference in the conventions for V_{Λ} and $G_{\Lambda, \infty}$ ((6.12) versus (6.11)) is no obstacle to interpret V_{Λ} as an effective potential and, hence, to interpret the corresponding flow operators

$$\{\mathbf{S}_{\Lambda}^{-1} \circ \mathbf{S}_{\Lambda_0} \mid 0 \leq \Lambda \leq \Lambda_0 < \infty\} \quad (6.13)$$

as a version of Wilson's RG. Proceeding heuristically, we are now going to show that the restriction of the operators (6.13) to \mathcal{F}_{loc} can be approximated by a subfamily of the Stückelberg–Petermann RG, for Λ, Λ_0 large enough.

For this purpose we use that, for a renormalizable model, the limit $\Lambda \rightarrow \infty$ of \mathbf{S}_{Λ} exists if one adds suitable *local* counterterms (analogously to (6.2), (6.3)). This addition of local counterterms can be described by $V \rightarrow Z_{\Lambda}(V)$ with an element Z_{Λ} of the Stückelberg–Petermann group. In detail [2]: for all $0 < \Lambda < \infty$ there exists a $Z_{\Lambda} \in \mathcal{R}_0$ with

$$\lim_{\Lambda \rightarrow \infty} \mathbf{S}_{\Lambda} \circ Z_{\Lambda} = \mathbf{S}. \quad (6.14)$$

By \mathcal{R}_0 we mean the version of the Stückelberg–Petermann RG which is defined by requiring only the conditions of starting element, locality and field independence. Since usually \mathbf{S}_{Λ} does not satisfy Poincaré invariance, almost homogeneous scaling and unitarity (and possibly violates also smoothness in $m \geq 0$), we may not expect that Z_{Λ} fulfils the corresponding conditions.

With (6.14) we have $\lim_{\Lambda \rightarrow \infty} \mathbf{S}_{\Lambda} \circ Z_{\Lambda} = \mathbf{S} = \lim_{\Lambda_0 \rightarrow \infty} \mathbf{S}_{\Lambda_0} \circ Z_{\Lambda_0}$, from which we conclude that

$$\mathbf{S}_{\Lambda}^{-1} \circ \mathbf{S}_{\Lambda_0} \big|_{\mathcal{F}_{\text{loc}}} \approx Z_{\Lambda} \circ Z_{\Lambda_0}^{-1} \in \mathcal{R}_0 \quad \text{for } \Lambda, \Lambda_0 \rightarrow \infty. \quad (6.15)$$

That is, for Λ, Λ_0 large enough, the restriction of the flow operators $\mathbf{S}_{\Lambda}^{-1} \circ \mathbf{S}_{\Lambda_0}$ to \mathcal{F}_{loc} can be approximated by the two-parametric subfamily $Z_{\Lambda} \circ Z_{\Lambda_0}^{-1}$ of the Stückelberg–Petermann group \mathcal{R}_0 .

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